

Decorrelation of GRACE time variable gravity field solutions using full covariance information

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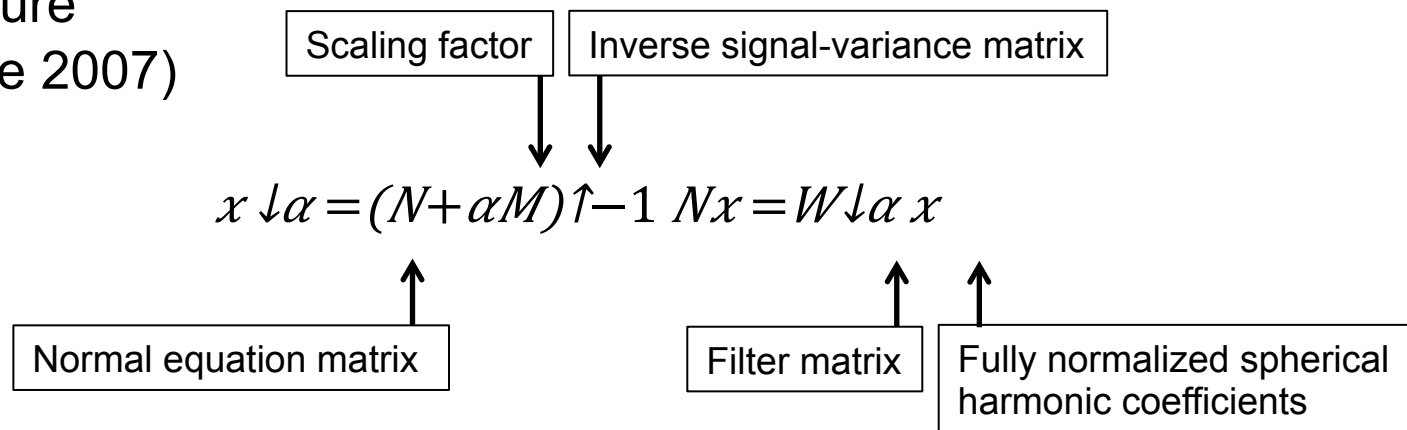
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 - ITSG2014 (d/o 60 & 90)
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Decorrelation of GRACE like gravity fields

Procedure
(Kusche 2007)



Data used for closed-loop simulations:

M (AO)HIS model data (Gruber et al., 2011)

N Simulated GRACE-like full covariance information

GRACE-like means: GRACE orbits & GRACE-like observations and noise (acceleration differences) for one year

Results from closed loop simulations

Effect of different error covariances:

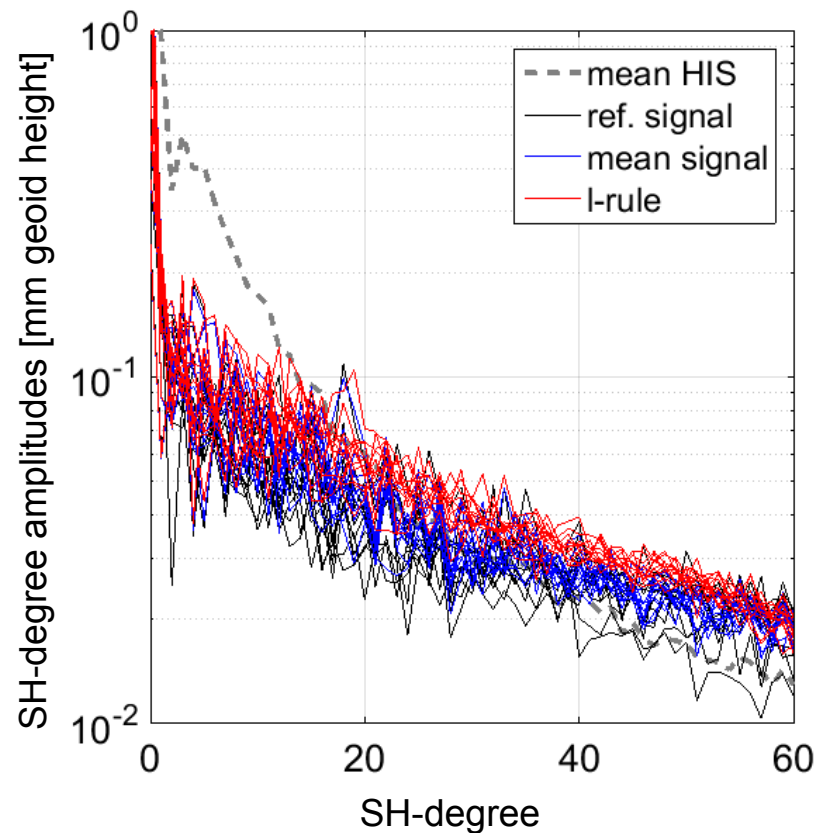
- Full
- Orderblock
- Diagonal

Effect of different signal variances:

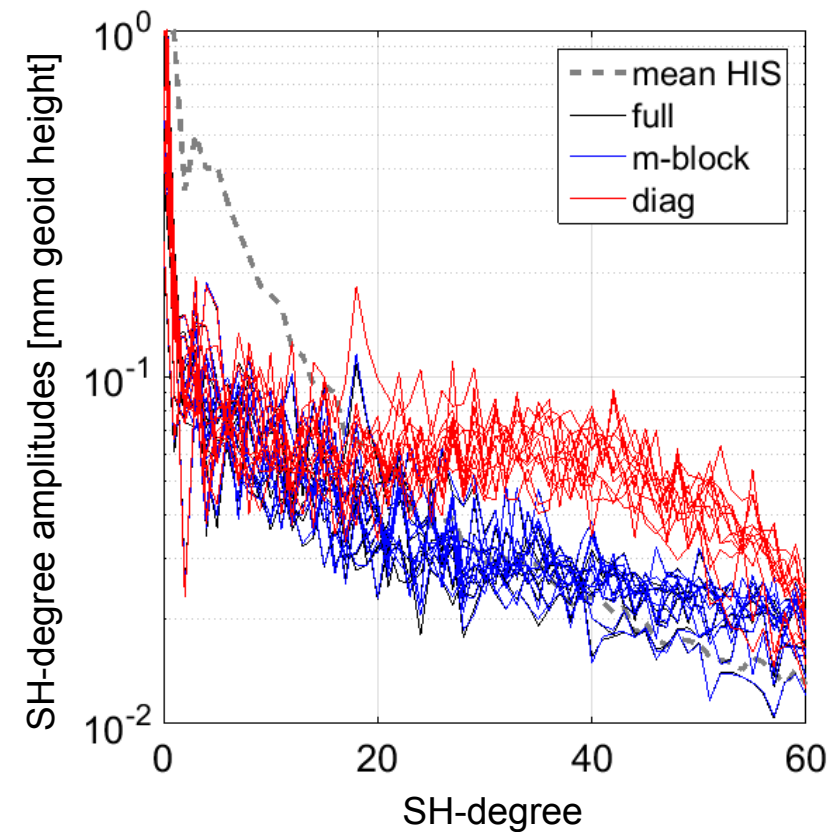
- True reference signal
- Mean signal (mean signal variance)
- L-rule (degree dependent only)

Residuals from closed loop simulations

With different signal variances



With different error covariances



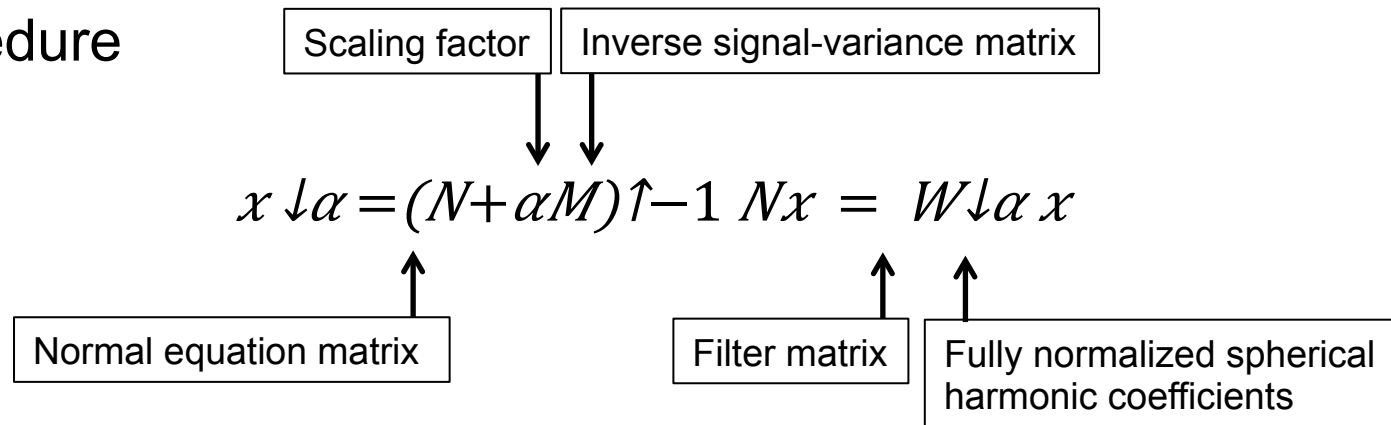
- Mean signal variance gives 9% improvement w.r.t. l-rule
- Full error covariance gives 37% improvement w.r.t. diagonal
- Static error covariance costs 10%-30% deterioration

Looking at cumulative geoid errors 5

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Decorrelation of real data

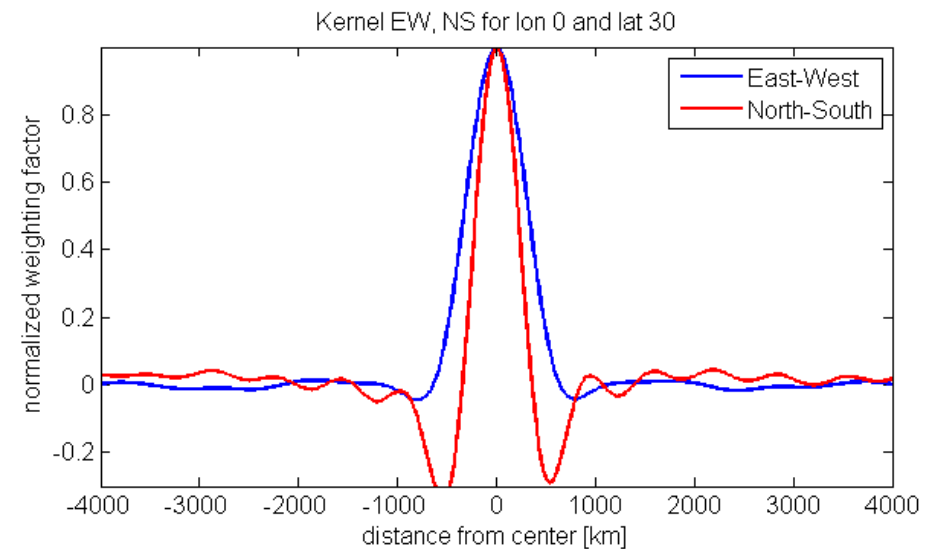
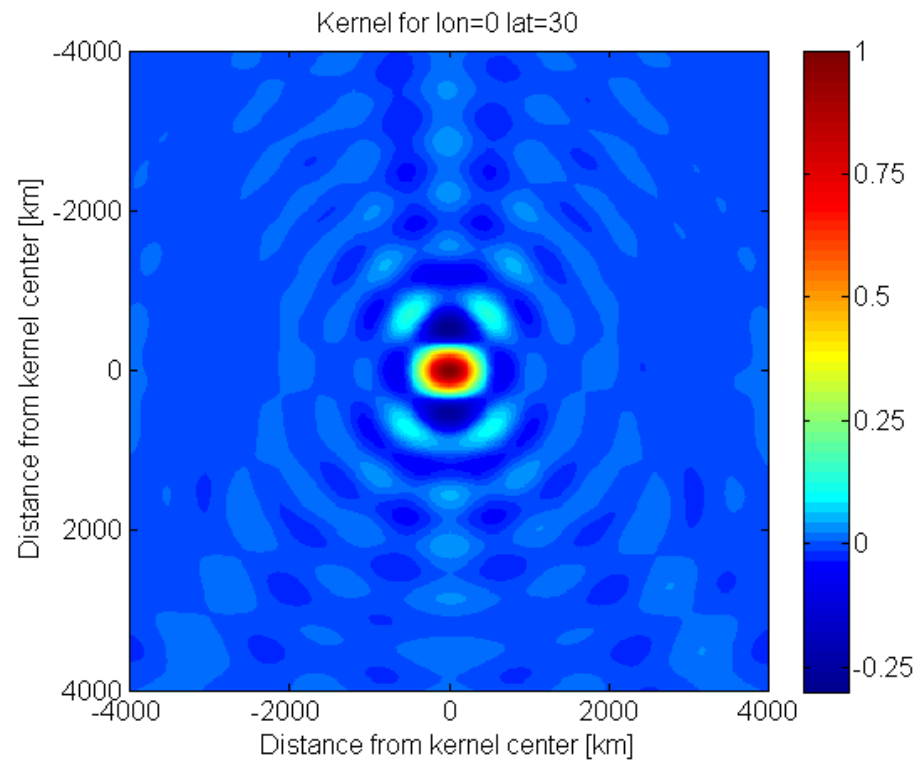
Procedure



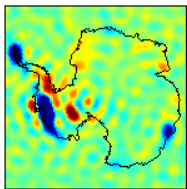
Data used for decorrelation of real data:

- M (AO)HIS model data (mean Jan to Dec per Coefficient)
(Gruber et al., 2011 & Dobsław et al., 2015)
- N Full real GRACE covariance information from ITSG 2014
(Mayer-Gürr et al., 2014) & GFZ RL05a (Dahle et al., 2013)

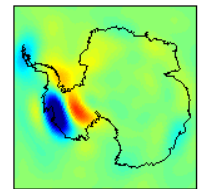
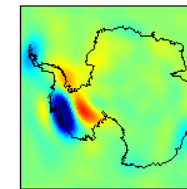
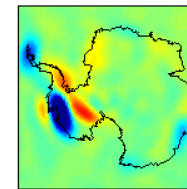
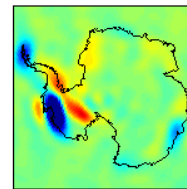
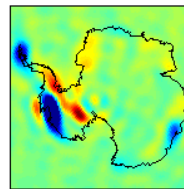
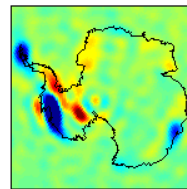
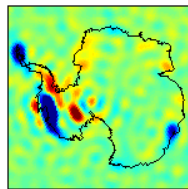
Filter kernels 1D and 2D



Decorrelation of real data – ITSG2014 GRACE (do 90)

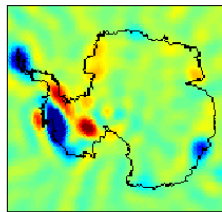


~175km

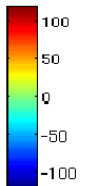
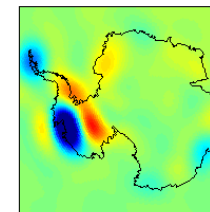
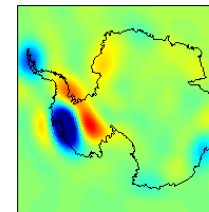
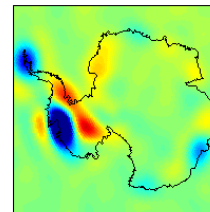
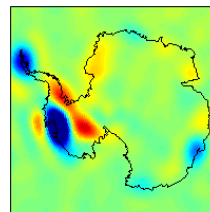
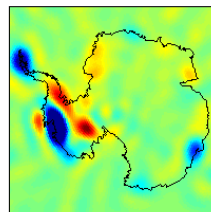


steps of about 40km

~450km



**DDK 8
(180km)**



**DDK 3
(330km)**

Units: mm ewh / year linear trend
All estimates from ITSG2014

Intercomparison to other post processing strategies

Results will be tested against:

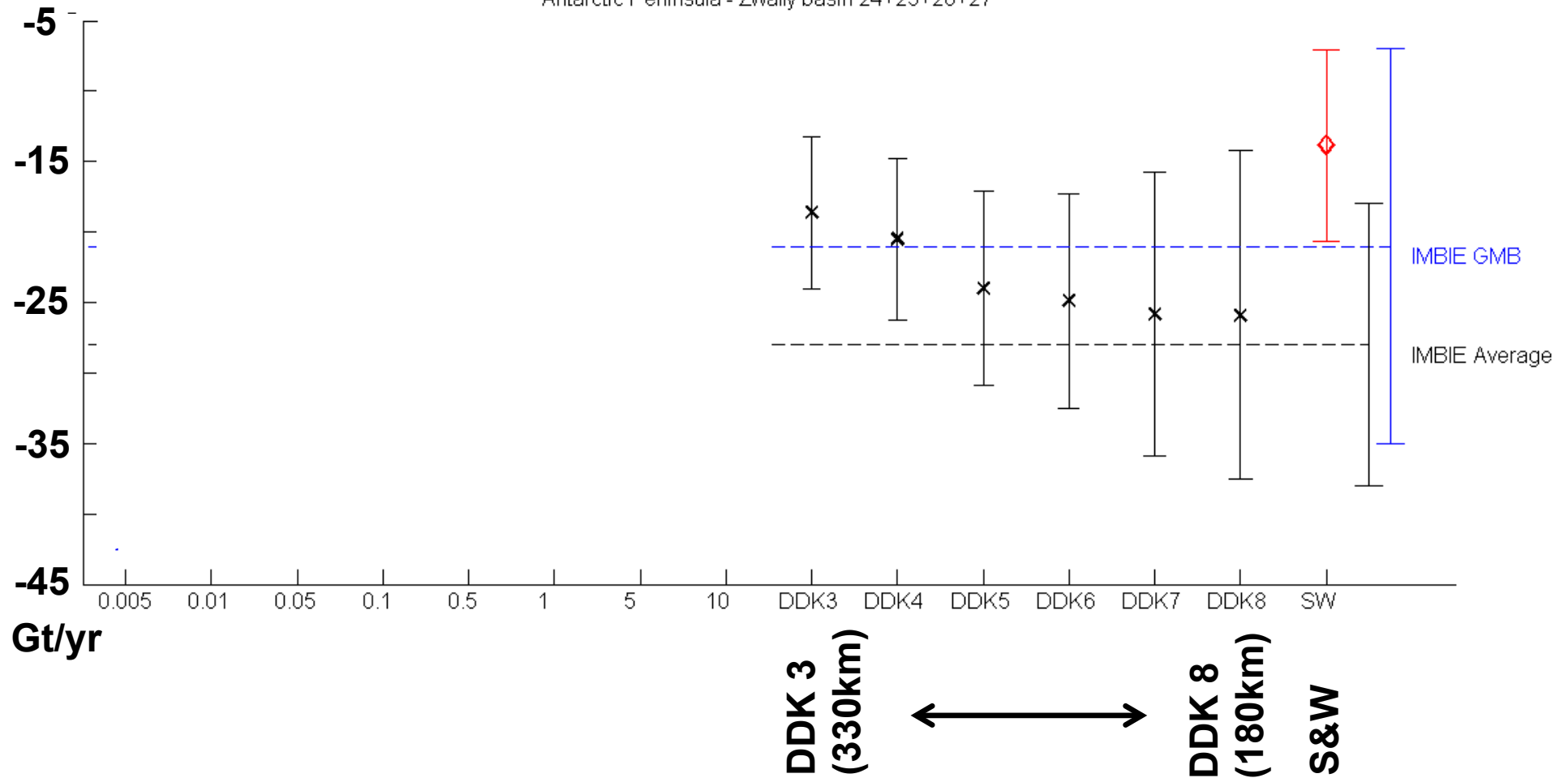
- Anisotropic Swenson & Wahr Type filter
(optimized for Antarctic region)
- DDK decorrelation filter (Kusche, 2009)

In terms of:

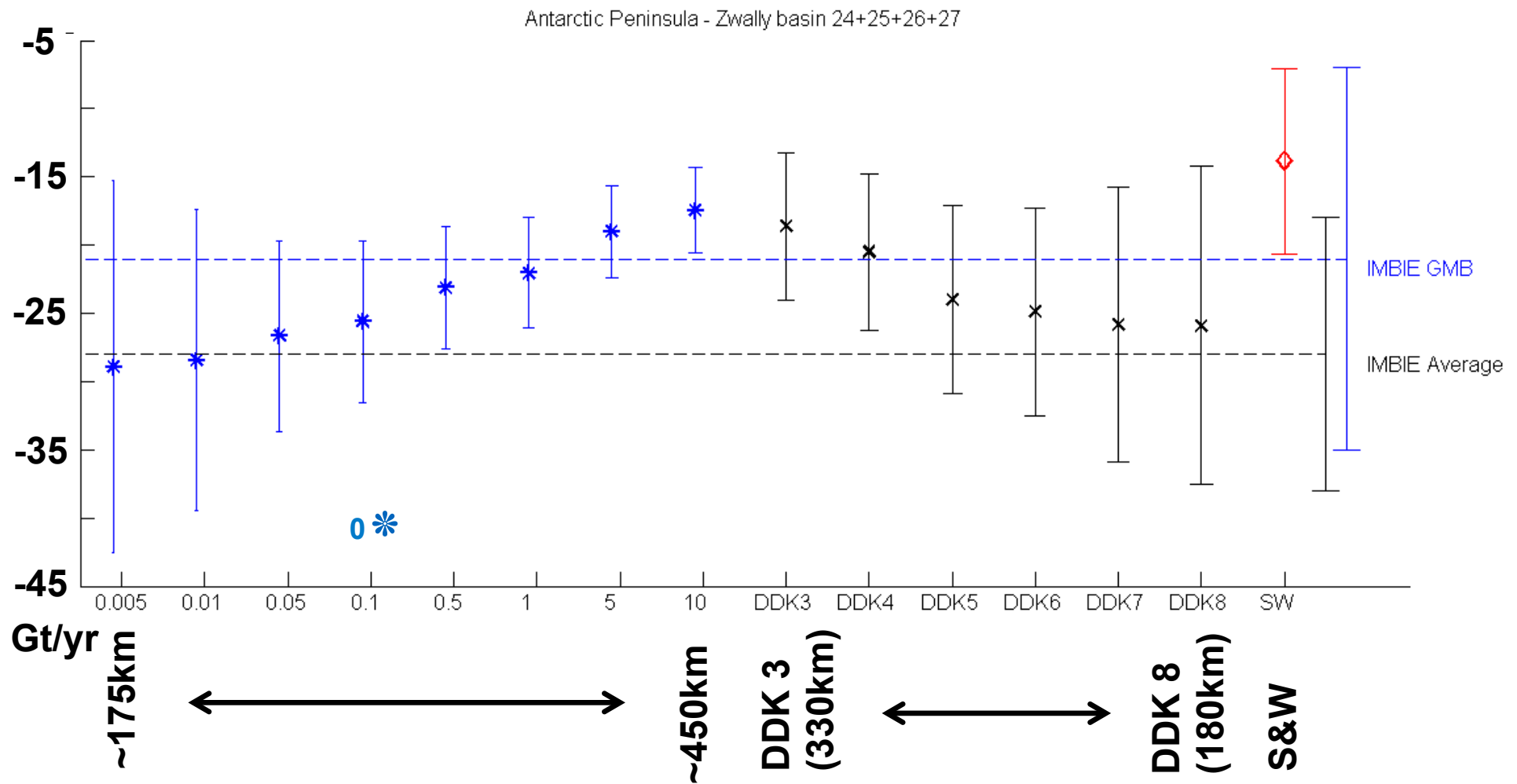
- estimated trend results
- integrated mass change on basin scale

Integrated mass change

Antarctic Peninsula - Zwally basin 24+25+26+27

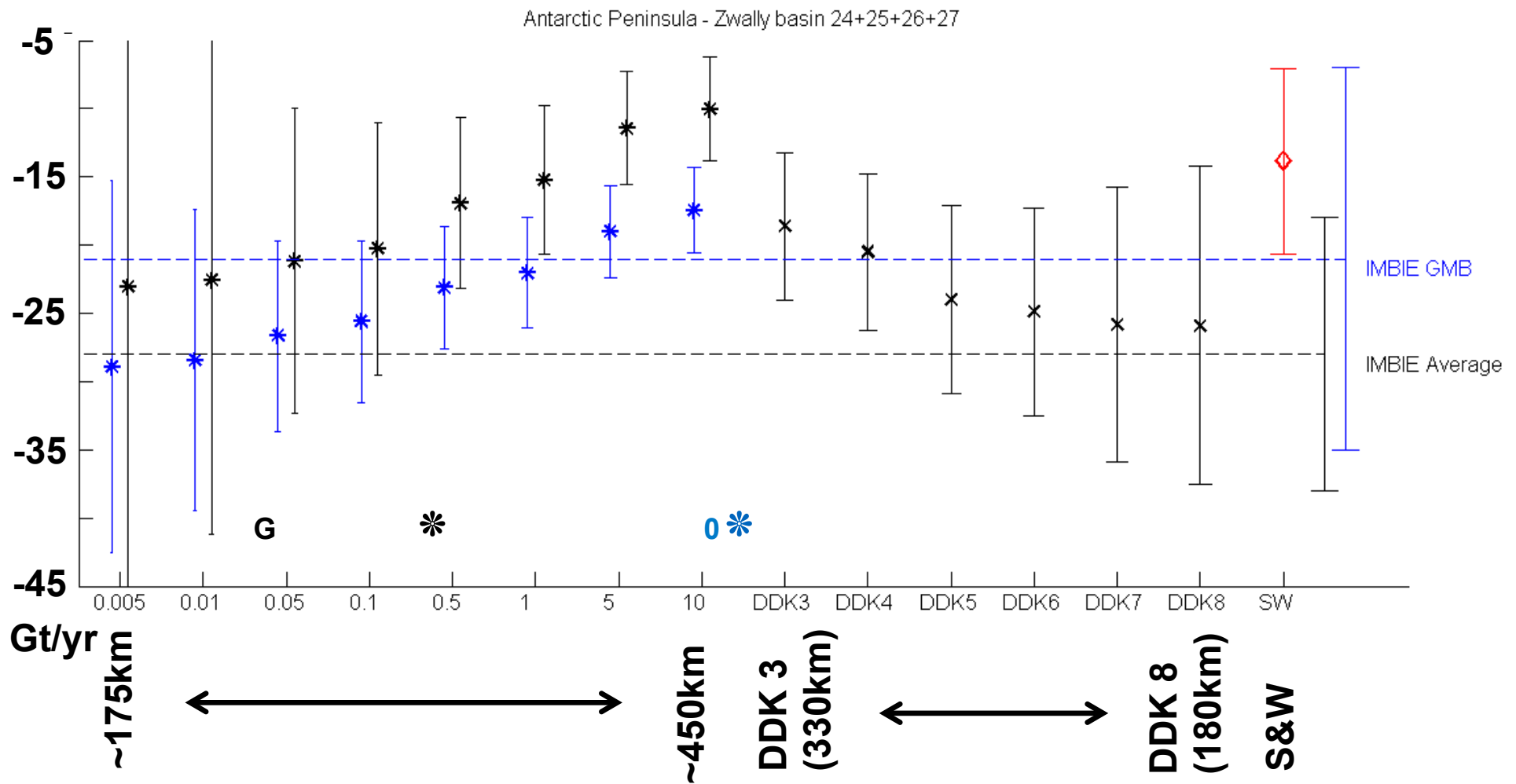


Integrated mass change



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Integrated mass change



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Conclusion & Outlook

- Best suitable post processing strategy depends on target area and characteristics of target signal
- Largest deterioration with L-rule signal and diagonal error covariance → Utilization of “mean” signal variance and time variable error covariance information is advisable
- Method delivers competitively small formal errors for integrated mass change
- Determination of signal variance in an iterative procedure minimizing utilization of apriori information.

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